

# FEM calculations



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# Introduction.

- Why use FEM?
  - Better consideration of deformation effects, for example on shaft calculation and thus CA, or  $K_h\beta$ .
  - More accurate calculation of root stresses, especially in cases that the standards do not cover so good.

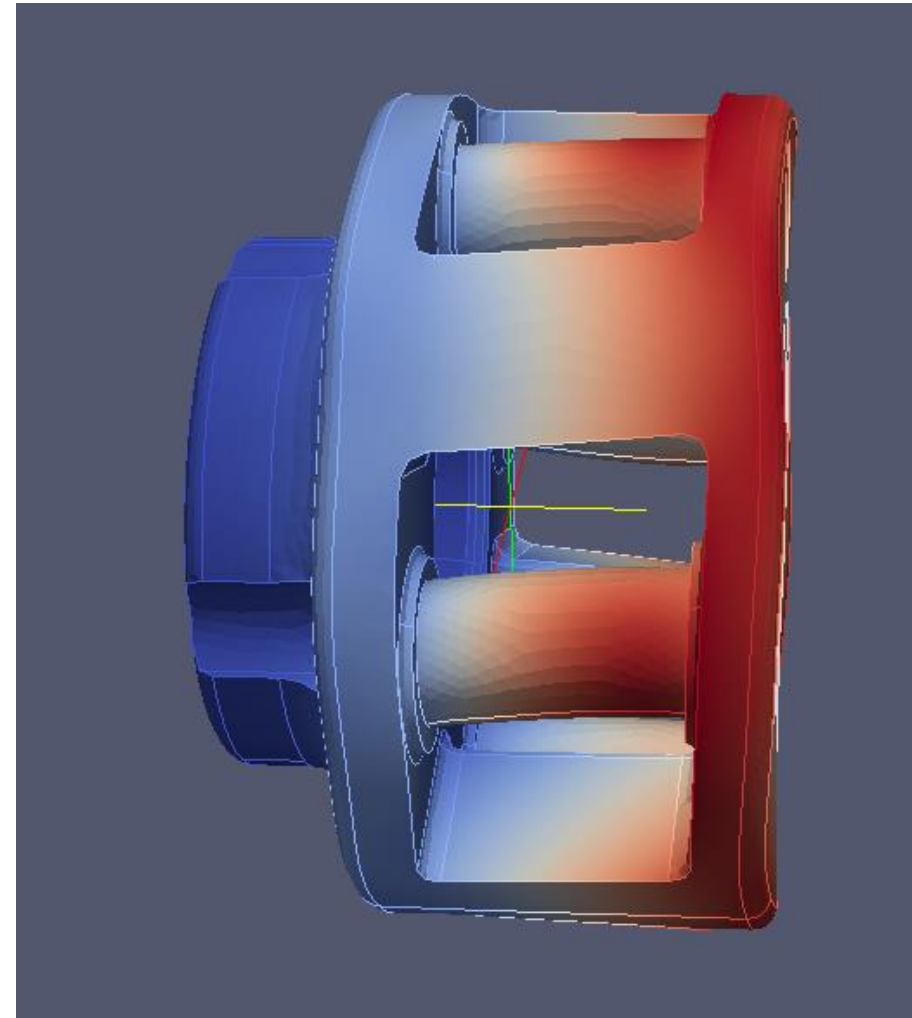
## FEM packages used.

	Pre – Post processor:	Solver:
	 <a href="http://www.salome-platform.org/">http://www.salome-platform.org/</a>	 <a href="http://www.code-aster.org/">http://www.code-aster.org/</a>
Developing partners	EDF, EADS, Bureu Veritas	EDF, Universities
Year of first version	2000	1991, open source since 2001
Platform	Linux, Windows	Linux, Windows
Development cycle	Every 6 months	Stable operating version every 2 years. Fixes every month.
Other	6000 tests. Post processing based on Paraview. Automatic mesh generation & refinement	2000 tests, nuclear industry quality, 14000 pages of user's manual

Analyses currently available.

## Planet carrier deformation.

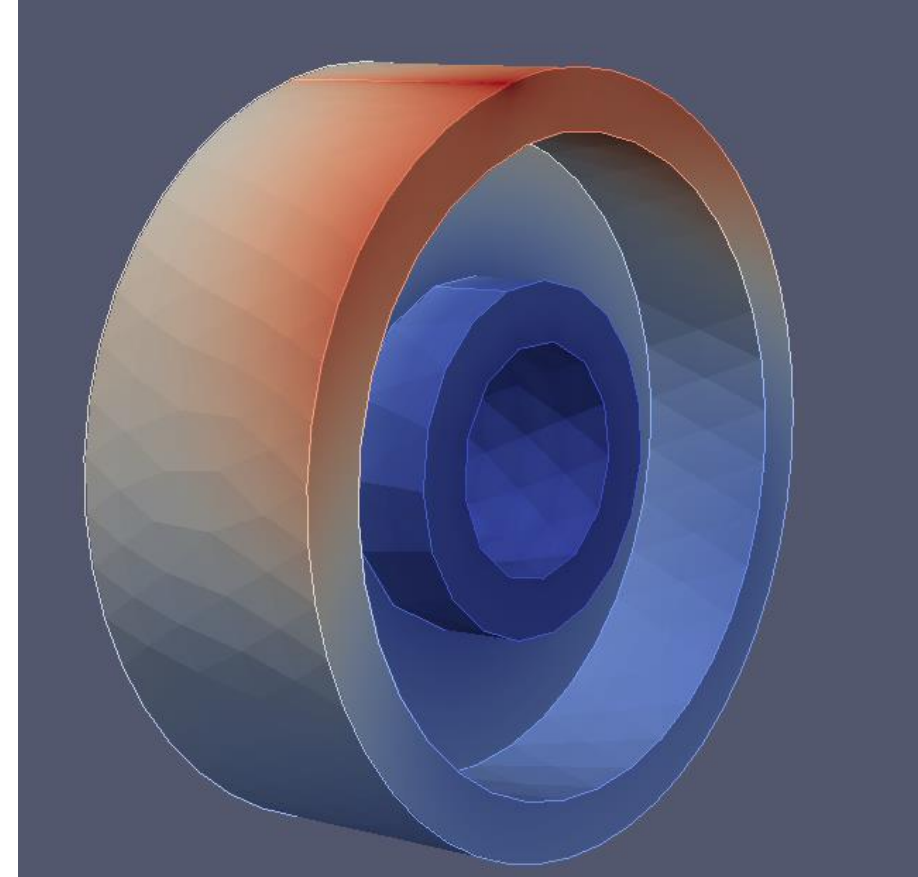
- Single and double sided.
- Different geometric inputs (e.g. straight flanks, cavities, etc).
- Import of STEP file



Analyses currently available.

## Gear body deformation

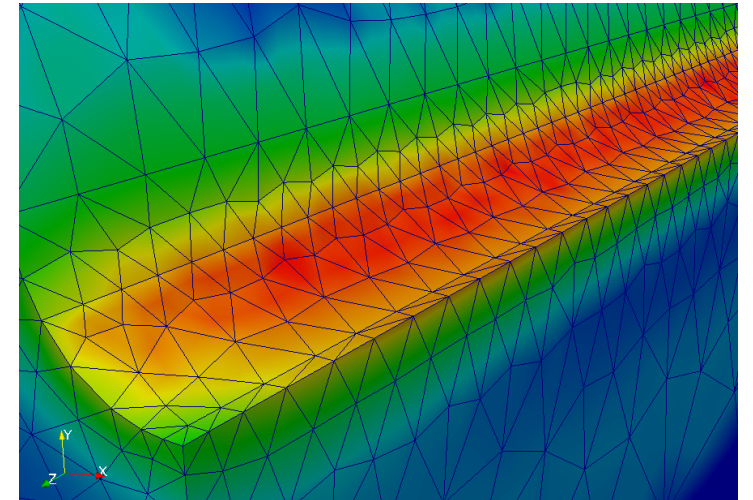
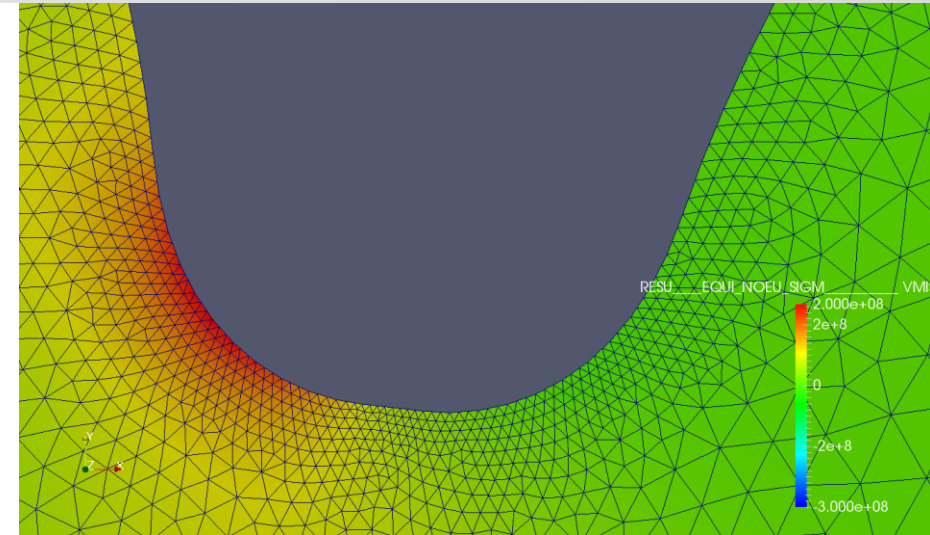
- Different geometric inputs.
- Straight or inclined web.
- Deformation or stiffness matrix output.
- Stiffness matrix can be imported and used in tooth trace modification or contact analysis calculation.



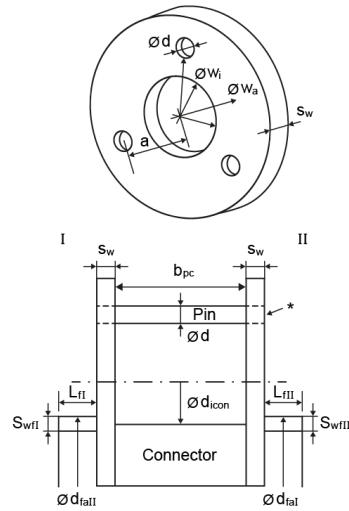
Analyses currently available.

## Gear root stress (both 2D and 3D).

- Geometric input directly from KISSsoft tooth form.
- Load from contact analysis (3D).
- Different types of boundary conditions.



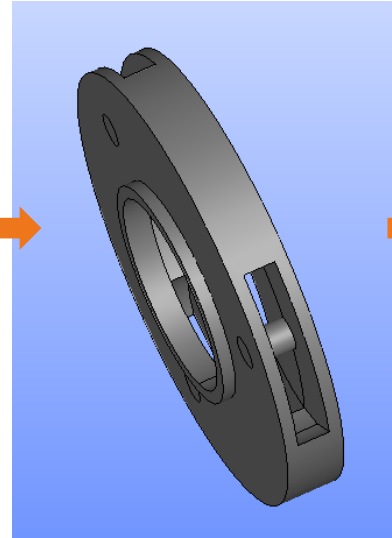
# Calculation steps.



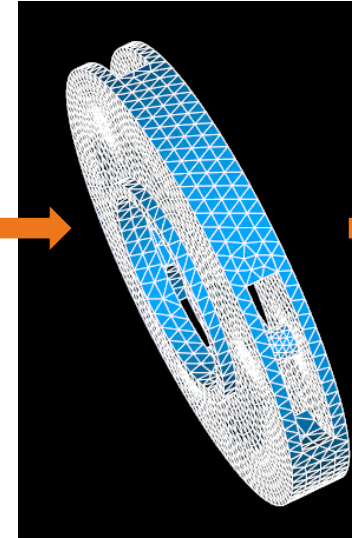
1. Parametric model



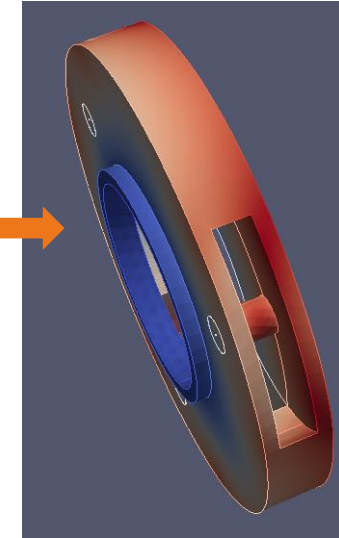
User input in KISSsoft



2. 3D model



3. FEM mesh

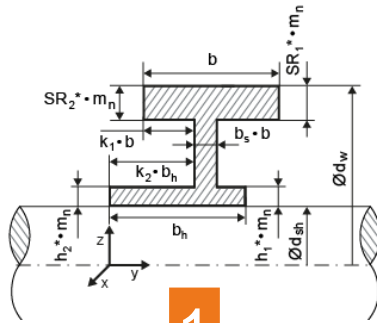


4. Results



Automatic FEM analysis  
in Salome and code\_aster

# Integration procedure.



```

if (coordsDif > 1e-14):
    Edge = geompy.MakeEdge(Vertex1, Vertex2)
    Wire = geompy.MakeWire([Edge], 1e-007)
    IF (%i==0) THEN {mGearBody.innerCylinderLine}
    IF (%i==0) THEN {mGeometry.isInternalGear}
        geompy.addToStudy( Wire, 'ShaftLine' )
    ELSE
        geompy.addToStudy( Wire, 'LoadLine' )
    END;
END;
END;
IF (%i==0) THEN {mGearBody.outerCylinderLine}
    outerRadicous = z
    center1 = geompy.MakeVertex(0, %3.4f, 0) {mGearBody.pointCoords[#id1, 1]}
    center2 = geompy.MakeVertex(0, %3.4f, 0) {mGearBody.pointCoords[#id2, 1]}
    Circle = geompy.MakeCircle(center1, OY, outerRadicous)
    geompy.addToStudy( Circle, 'Circle1' )
    Circle = geompy.MakeCircle(center2, OY, outerRadicous)
    geompy.addToStudy( Circle, 'Circle2' )
IF (%i==0) THEN {mGeometry.isInternalGear}
    geompy.addToStudy( Wire, 'LoadLine' )
ELSE
    geompy.addToStudy( Wire, 'ShaftLine' )
END;
END;

##Continue with the other connection points in a loop
FOR count=1 TO %i BY 1 DO {mGearBody.pointCoords.size()-1}
SETVAR id1 = %i {mGearBody.conPoint1[#count]}
x = %3.4f(mGearBody.pointCoords[#id1, 0])
y = %3.4f(mGearBody.pointCoords[#id1, 1])
z = %3.4f(mGearBody.pointCoords[#id1, 2])
Vertex1 = geompy.MakeVertex(x, y, z)
SETVAR id2 = %i {mGearBody.conPoint2[#count]}
    
```



```

88
89 if (coordsDif > 1e-14):
90
91     Edge = geompy.MakeEdge(Vertex1, Vertex2)
92
93     Wire = geompy.MakeWire([Edge], 1e-007)
94
95     geompy.addToStudy( Wire, 'ShaftLine' )
96
97
98
99 ##Continue with the other connection points in a loop
100
101 x = 0.0000
102
103 y = 0.0450
104
105 z = 0.0200
106
107 Vertex1 = geompy.MakeVertex(x, y, z)
108
109 x = 0.0000
110
111 y = 0.0450
112
113 z = 0.0300
114
115 Vertex2 = geompy.MakeVertex(x, y, z)
116
    
```



```

C:\Windows\system32\cmd.exe
DDL_INFO_FGROUP_NO<HOLD>.
LIAISON_XFEM<NON>.
MODELE-MOD.
?

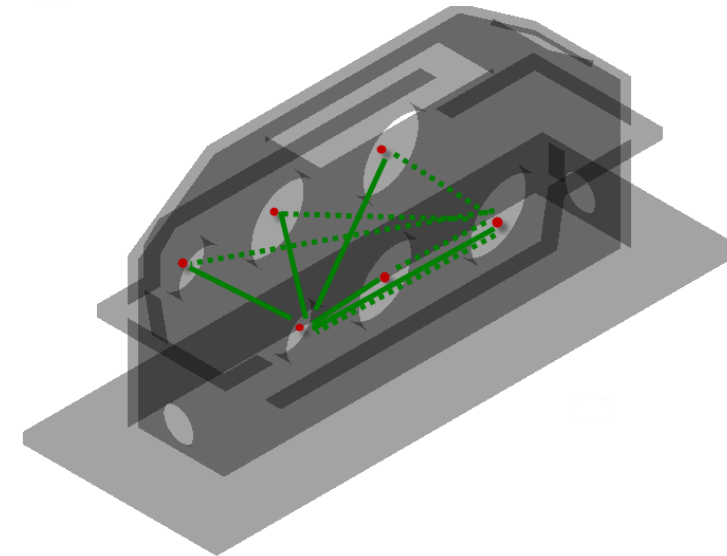
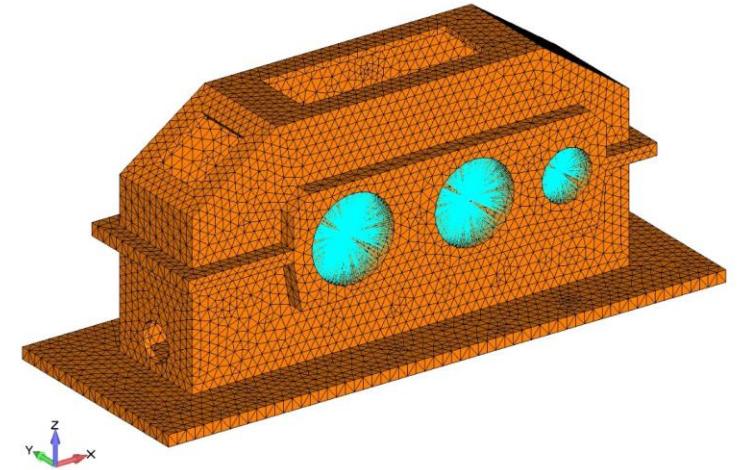
# USAGE DE LA MEMOIRE JEVEUR : 15.96 Mo <MAXIMUM ATTEINT : 17.92 Mo>
# - MEMOIRE DYNAMIQUE CONSOMEE : 5.29 Mo <MAXIMUM ATTEINT : 14.36 Mo>
# FIN COMMANDE NO : 0000 USER+SYST : 0.02s SYST : 0.00s ELAPS : 0.00s

# COMMANDE NO : 0000 CONCEPT DE TYPE : char_meca
# Force=HFE_CHAR_MECH(FORCE_ARETE=_PCH-S-ES,
# PY=0,0,
# GROUP=0, LONDM',
# FZ=0,0).
INFO-1:
VERI_NORM=OUI.
LIAISON_XFEM=NON.
MODELE-MOD.
?
    
```



# Housing deformation.

- Read-in of the finite element reduced stiffness matrix:
  - “spring like” constants connecting the “bearing nodes” of the FE grid, for all degrees of freedom.
- Interfaces to:
  - ANSYS
  - NASTRAN
  - ABAQUS
  - ALTAIR OptiStruct



# Conclusions

1. Robust open source FEA software integrated with KISSsoft (seamless integration).
2. Calculations:
  - Gear body deformation.
  - Planet carrier deformation.
  - Tooth root stress.
  - Housing stiffness (through file input).
3. Powerful post processing tool.

Thank you for your attention!

Sharing Knowledge

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